# ACSV: help wanted from computer algebra(ists) 

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ICMS
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## Standing assumptions

- We use boldface to denote a multi-index: $\mathbf{z}=\left(z_{1}, \ldots, z_{d}\right)$, $\mathbf{r}=\left(r_{1}, \ldots, r_{d}\right)$. Similarly $\mathbf{z}^{\mathbf{r}}=z_{1}^{r_{1}} \ldots z_{d}^{r_{d}}$.


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- To avoid discussing complicated topology, assume all coefficients of $F$ are nonnegative.


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- Lattice walks in quarter plane, negative drift:

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\begin{aligned}
& G=(1+x)\left(1-2 t\left(1+x^{2}\right)\right) \\
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- Cubical tensors


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- For $\mathbf{p} \in \operatorname{contrib}(\overline{\mathbf{r}})$, there is a full asymptotic series $\mathcal{A}(\mathbf{p})$ depending on the type of singularity at $\mathbf{p}$. Each term is computable from finitely many derivatives of $G$ and $H$ at $\mathbf{z}$.


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- This yields an asymptotic expansion

$$
a_{\mathbf{r}} \sim \sum_{\mathbf{p} \in \operatorname{contrib}(\overline{\mathbf{r}})} \mathbf{p}^{-\mathbf{r}} \mathcal{A}(\mathbf{p})
$$

that is uniform on compact subsets of directions, provided the geometry at $\mathbf{p}$ does not change.

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- There is an element of $\operatorname{contrib}(\overline{\mathbf{r}})$ having all positive coordinates.
- We have full results for smooth and transverse multiple local geometry of critical points.
- We can check $\mathbf{p} \in \operatorname{contrib}(\overline{\mathbf{r}})$ by checking whether $\overline{\mathbf{r}}$ belongs to a certain real positive cone $K(\mathbf{p})$.


## Simplest asymptotic formulae

- Smooth point:

$$
a_{\mathbf{r}} \sim \mathbf{z}_{*}(\overline{\mathbf{r}})^{-\mathbf{r}} \sqrt{\frac{1}{(2 \pi|\mathbf{r}|)^{d-1} \kappa\left(\mathbf{z}_{*}(\overline{\mathbf{r}})\right)}} \frac{G\left(\mathbf{z}_{*}(\overline{\mathbf{r}})\right)}{\left|\nabla_{\log } H\left(\mathbf{z}_{*}(\overline{\mathbf{r}})\right)\right|}
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where $|\mathbf{r}|=\sum_{i} r_{i}$ and $\kappa$ is the Gaussian curvature of $\log \mathcal{V}$ at $\log \mathbf{z}_{*}(\overline{\mathbf{r}})$.

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- The Gaussian curvature can be computed explicitly in terms of derivatives of $H$ to second order.
- Simplest multiple point:

$$
a_{\mathbf{r}} \sim \mathbf{z}_{*}(\overline{\mathbf{r}})^{-\mathbf{r}} G\left(\mathbf{z}_{*}(\overline{\mathbf{r}})\right) \operatorname{det} J\left(\mathbf{z}_{*}(\overline{\mathbf{r}})\right)^{-1}
$$

where $J$ is the Jacobian matrix $\left(\partial H_{i} / \partial z_{j}\right)$ and $H=\prod_{i} H_{i}$.

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- Main features:
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- Auxiliary functions to convert $G / H$ to various forms.


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- Exception handling.
- Putting everything together (non-interactive mode).


## Medium level improvements

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- Improvements to speed of higher order asymptotic computations.


## Hörmander's explicit formula for integral asymptotics

 For an isolated nondegenerate stationary point $\mathbf{0}$ in dimension $d$,$$
I(\lambda) \sim\left(\operatorname{det}\left(\frac{\lambda f^{\prime \prime}(\mathbf{0})}{2 \pi}\right)\right)^{-1 / 2} \sum_{k \geq 0} \lambda^{-k} L_{k}(A, f)
$$

where $L_{k}$ is a differential operator of order $2 k$ evaluated at $\mathbf{0}$ :

$$
\begin{aligned}
\underline{f}(t) & =f(t)-(1 / 2) t f^{\prime \prime}(\mathbf{0}) t^{T} \\
\mathcal{D} & =\sum_{a, b}\left(f^{\prime \prime}(\mathbf{0})^{-1}\right)_{a, b}\left(-\mathrm{i} \partial_{a}\right)\left(-\mathrm{i} \partial_{b}\right) \\
L_{k}(A, f) & =\sum_{l \leq 2 k} \frac{\mathcal{D}^{l+k}\left(A \underline{f}^{l}\right)(\mathbf{0})}{(-1)^{k} 2^{l+k} l!(l+k)!} .
\end{aligned}
$$

For example $L_{0}(A, f)=A$,
$L_{1}(A, f)=-\mathcal{D}(A) / 2-\mathcal{D}^{2}(A \underline{f}) / 8-\mathcal{D}^{3}\left(A \underline{f}^{2}\right) / 48$.

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- Detecting whether we are in this case is easy (irreducible factors are everywhere smooth).
- However if we are not in this case, we currently have no way to proceed. Such problems do arise rather frequently in applications.


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- Our methods are analytic, so computations should be carried out in the analytic local ring (the ring of germs of holomorphic functions at a point).


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- Our methods are analytic, so computations should be carried out in the analytic local ring (the ring of germs of holomorphic functions at a point).
- Computation in this ring is trickier than in polynomial rings. However there is a theory of computation in local rings and apparently SINGULAR implements some of it.
- Help wanted in finding the state of the art!


## Example (local factorization of lemniscate)

- Given $F=1 / H$ where $H$ is irreducible, given by $H(x, y)=$ $19-20 x-20 y+5 x^{2}+14 x y+5 y^{2}-2 x^{2} y-2 x y^{2}+x^{2} y^{2}$.


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- At $(1,1)$, changing variables to $h(u, v):=H(1+u, 1+v)$, we see that $h(u, v)=4 u^{2}+10 u v+4 v^{2}+C(u, v)$ where $C$ has no terms of degree less than 3 .


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- The quadratic part factors into distinct factors, showing that $(1,1)$ is a transverse multiple point.
- The current implementation does not deal with this at all, but we can compute by hand in this case to see that $a_{r r} \sim 1 / 6$.


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- Thus it is not always even obvious whether a point is smooth, and vanishing numerator affects exponential rate.


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- Here $F=G / H$ where $G=x-y, H_{1}=1-(1 / 6) x-(5 / 6) y^{2}$, $H_{2}=1-(5 / 6) x^{2}-(1 / 6) y^{2}, H=H_{1} H_{2}$.


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- Our current implementation gives $a_{r r} \sim 0$, but this is wrong.
- Here $G$ is not in the ideal $\left\langle H_{1}, H_{2}\right\rangle$ of the polynomial ring.
- We need to go to the local analytic ring. Ring theoretic arguments (Nullstellensatz, Noetherianity) show that $G$ must lie in the ideal generated by $H_{1}, H_{2}$ and a simplification again occurs. Again we will have smooth point behaviour.


## Example (effect of numerator, II)

- Here $F=G / H$ where $G=x-y, H_{1}=1-(1 / 6) x-(5 / 6) y^{2}$, $H_{2}=1-(5 / 6) x^{2}-(1 / 6) y^{2}, H=H_{1} H_{2}$.
- Again $\mathcal{V}$ is clearly smooth at every point except $(1,1)$.
- Our current implementation gives $a_{r r} \sim 0$, but this is wrong.
- Here $G$ is not in the ideal $\left\langle H_{1}, H_{2}\right\rangle$ of the polynomial ring.
- We need to go to the local analytic ring. Ring theoretic arguments (Nullstellensatz, Noetherianity) show that $G$ must lie in the ideal generated by $H_{1}, H_{2}$ and a simplification again occurs. Again we will have smooth point behaviour.
- How to do this algorithmically?

