ACSV: help wanted from computer algebra(ists)

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- To avoid discussing complicated topology, assume all coefficients of F are nonnegative.

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- This yields an asymptotic expansion

$$a_{\mathbf{r}} \sim \sum_{\mathbf{p} \in \operatorname{contrib}(\overline{\mathbf{r}})} \mathbf{p}^{-\mathbf{r}} \mathcal{A}(\mathbf{p})$$

that is uniform on compact subsets of directions, provided the geometry at \mathbf{p} does not change.

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- ► There is an element of contrib(r) having all positive coordinates.
- We have full results for smooth and transverse multiple local geometry of critical points.
- We can check p ∈ contrib(r̄) by checking whether r̄ belongs to a certain real positive cone K(p).

Simplest asymptotic formulae

Smooth point:

$$a_{\mathbf{r}} \sim \mathbf{z}_{*}(\overline{\mathbf{r}})^{-\mathbf{r}} \sqrt{\frac{1}{(2\pi|\mathbf{r}|)^{d-1}\kappa(\mathbf{z}_{*}(\overline{\mathbf{r}}))}} \frac{G(\mathbf{z}_{*}(\overline{\mathbf{r}}))}{|\nabla_{\log}H(\mathbf{z}_{*}(\overline{\mathbf{r}}))|}$$

where $|\mathbf{r}| = \sum_i r_i$ and κ is the Gaussian curvature of $\log \mathcal{V}$ at $\log \mathbf{z}_*(\overline{\mathbf{r}})$.

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► The Gaussian curvature can be computed explicitly in terms of derivatives of *H* to second order.

Simplest asymptotic formulae

Smooth point:

$$a_{\mathbf{r}} \sim \mathbf{z}_{*}(\overline{\mathbf{r}})^{-\mathbf{r}} \sqrt{\frac{1}{(2\pi|\mathbf{r}|)^{d-1}\kappa(\mathbf{z}_{*}(\overline{\mathbf{r}}))}} \frac{G(\mathbf{z}_{*}(\overline{\mathbf{r}}))}{|\nabla_{\log}H(\mathbf{z}_{*}(\overline{\mathbf{r}}))|}$$

where $|\mathbf{r}| = \sum_i r_i$ and κ is the Gaussian curvature of $\log \mathcal{V}$ at $\log \mathbf{z}_*(\overline{\mathbf{r}})$.

- ► The Gaussian curvature can be computed explicitly in terms of derivatives of *H* to second order.
- Simplest multiple point:

$$a_{\mathbf{r}} \sim \mathbf{z}_{*}(\overline{\mathbf{r}})^{-\mathbf{r}} G(\mathbf{z}_{*}(\overline{\mathbf{r}})) \det J(\mathbf{z}_{*}(\overline{\mathbf{r}}))^{-1}$$

where J is the Jacobian matrix $(\partial H_i/\partial z_j)$ and $H = \prod_i H_i$.

1. Conversion of G/H to various forms.

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2. Computing $\operatorname{crit}(\overline{\mathbf{r}})$.

- 1. Conversion of G/H to various forms.
- 2. Computing $\operatorname{crit}(\overline{\mathbf{r}})$.
- 3. Classification of local geometry at critical points.

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4. Determining which critical points contribute.

- 1. Conversion of G/H to various forms.
- 2. Computing $\operatorname{crit}(\overline{\mathbf{r}})$.
- 3. Classification of local geometry at critical points.
- 4. Determining which critical points contribute.
- 5. Explicit formulae for higher order asymptotics.

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• Auxiliary functions to convert G/H to various forms.

Status of package

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Classifying critical points by geometry.



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Exception handling.

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- Exception handling.
- Putting everything together (non-interactive mode).

Finding all the contributing singularities.

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Improvements to speed of higher order asymptotic computations.

Hörmander's explicit formula for integral asymptotics For an isolated nondegenerate stationary point **0** in dimension *d*,

$$I(\lambda) \sim \left(\det\left(\frac{\lambda f''(\mathbf{0})}{2\pi}\right) \right)^{-1/2} \sum_{k \ge 0} \lambda^{-k} L_k(A, f)$$

where L_k is a differential operator of order 2k evaluated at **0**:

$$\underline{f}(t) = f(t) - (1/2)tf''(\mathbf{0})t^T$$
$$\mathcal{D} = \sum_{a,b} (f''(\mathbf{0})^{-1})_{a,b}(-\mathrm{i}\partial_a)(-\mathrm{i}\partial_b)$$
$$L_k(A, f) = \sum_{l \le 2k} \frac{\mathcal{D}^{l+k}(A\underline{f}^l)(\mathbf{0})}{(-1)^k 2^{l+k} l! (l+k)!}.$$

For example $L_0(A, f) = A$, $L_1(A, f) = -\mathcal{D}(A)/2 - \mathcal{D}^2(A\underline{f})/8 - \mathcal{D}^3(A\underline{f}^2)/48$.

Bigger challenges

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- Detecting whether we are in this case is easy (irreducible factors are everywhere smooth).
- However if we are not in this case, we currently have no way to proceed. Such problems do arise rather frequently in applications.

Some conceptual difficulties

 Our methods are analytic, so computations should be carried out in the analytic local ring (the ring of germs of holomorphic functions at a point).

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- Computation in this ring is trickier than in polynomial rings. However there is a theory of computation in local rings and apparently SINGULAR implements some of it.

Some conceptual difficulties

- Our methods are analytic, so computations should be carried out in the analytic local ring (the ring of germs of holomorphic functions at a point).
- Computation in this ring is trickier than in polynomial rings. However there is a theory of computation in local rings and apparently SINGULAR implements some of it.

Help wanted in finding the state of the art!

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- ► The current implementation does not deal with this at all, but we can compute by hand in this case to see that a_{rr} ~ 1/6.

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Thus it is not always even obvious whether a point is smooth, and vanishing numerator affects exponential rate.

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- How to do this algorithmically?