# The probability of safe manipulation 

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COMSOC, Düsseldorf, 2010-09-16

Preliminaries

Safe manipulation

Algorithms for positional scoring rules

Further discussion

## - Outline

## What Google thinks this talk is about




AnalogHacking - Safe manipulation software for safe technicians Analog hacking offers free software for safe technicians to learn manipulation as well as other ls and a blog about how lock picking and safe analoghacking.com/ - Cached-Simiar

Safe-cracking - Lock manipulation
A selection of articles related to Safe-cracking - Lock manipulation
www.experiencefestival.com/safo-cracking_-_lock_manipulation - United States
Cached-Simiar
Poff Safecracking for the computer scientist
e Format: PDF/Adobe Acrobat - Quick View
21 Dec $2004 \ldots$... is usually called manipulation within the safe and vault trade, although, as we will later see, the techniques.
www.cryplo.com/papers/safolocks.pdt - Simiar
Joint Manipulation: Is it safe?
4 posts - 3 authors
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14 BEDFORD ROW, LONDON, WC1R 4ED TEL 0207306 6666. FAX 02073066611

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- The positional scoring rule determined by a vector $w$ with $w_{1} \geq w_{2} \geq \cdots \geq w_{m-1} \geq w_{m}$ assigns the usual score

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- In this talk tiebreaking is mostly not relevant, so we ignore it completely.


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- There is no claim that such strategic voting will take place, just that there is incentive to consider it.


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- The announced vote is safe if for all $x$, the outcome is never worse for these voters. In particular this applies to the maximal manipulation, where all voters of type $t$ switch. Note that a voter who ranks the sincere winner lowest can never vote unsafely.


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- The announced vote is safe if for all $x$, the outcome is never worse for these voters. In particular this applies to the maximal manipulation, where all voters of type $t$ switch. Note that a voter who ranks the sincere winner lowest can never vote unsafely.
- If in addition there is some $x$ for which the outcome is better for these voters, the profile is safely manipulable by type $t$ in direction $t^{\prime}$.


## Safe manipulation nonexample

- Let $m=5$ and use $w=(55,39,33,21,0)$. Suppose that there are 3 voters of each possible type, and 1 extra voter of type 12345 . The sincere winner is alternative 1 .


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- If 1 type 53124 voter votes instead as 35241 , alternative 2 wins; if 2 switch, alternative 3 wins; if 3 switch, alternative 4 wins.
- Thus such voters can both undershoot and overshoot in the same profile.


## Previous work

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－Hazon and Elkind studied the complexity of safe manipulation （COMSOC 2010，Tuesday）．Their main relevant results：
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- Hazon and Elkind studied the complexity of safe manipulation (COMSOC 2010, Tuesday). Their main relevant results:
- The results are strongly determined by the complexity of the tiebreaking algorithm.
- (IsSafe) Given $t, t^{\prime}$, and an anonymous rule, it is decidable in polynomial time whether safe manipulation is possible.
- (ExistsSafe) Given $t$, for a few common rules it is decidable in polynomial time whether safe manipulation is possible. Otherwise the answer is unknown.


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- Characterize those situations that are safely manipulable.
- Compute the (exact limiting, as $n \rightarrow \infty$ ) probability that a voting situation is safely manipulable, under the uniform distribution (IAC). The limiting probability of a tie is zero, so we can ignore tiebreaking.
- Let $S_{t, t^{\prime}}$ denote the set of situations safely manipulable by switching from $t$ to $t^{\prime}$. We seek the size of the union

$$
S:=\bigcup_{t \in \mathcal{T}} S_{t}:=\bigcup_{\substack{t \in \mathcal{T} \\ t \neq t^{\prime} \in \mathcal{T}}} S_{t, t^{\prime}}
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## Basic observations for positional scoring rules

- Let $a$ be the sincere winner. Call candidates preferred over $a$ by $t$ good and those ranked below $a$ bad. Manipulation is safe iff bad candidate never wins for any value of $x$, good candidate wins for some $x$.


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- Let $|c|(x)$ denote the score of $c$ when $x$ voters of type $t$ switch to $t^{\prime}$. This extends to real values of $x$ in the obvious way. The graphs $x \mapsto|c|(x)$ are straight lines (the score lines).

Algorithm for positional scoring rules, I

- Fix $t$ and $t^{\prime}$ and let $0 \leq x \leq\left|\mathcal{V}_{t}\right|$. Define

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& G(x)=\max \{|c|(x) \mid c \text { is good }\} \\
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- check the inequalities: $B\left(q_{k}\right)>\max \left\{G\left(q_{k}\right), U\left(q_{k}\right)\right\}$ and $G\left(q_{k}\right)>U\left(q_{k}\right)$. If first inequality holds, return SAFE $=$ false; if second holds, return MANIP $=$ true.


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- This determines whether a given situation belongs to $S_{t, t}$


## Algorithm for positional scoring rules, II

- I has size $O\left(m^{2}\right)$, and we simulate the voting rule once for each element of $I$. Each simulation requires $O(m)$ comparisons and $m$ score updates each of which requires $O(1)$ arithmetic operations on numbers of size $n$.


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- The algorithm simplifies greatly when $m=3$ : safe manipulation is possible if and only if the maximal manipulation elects a good candidate.
- We now have a characterization of manipulable situations by linear (in)equalities.


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－We then use inclusion－exclusion．
－This is very probably super－exponential in $m$ ，but polynomial in $n$ ．

## IAC computations via polytopes

- The scores are all linear functions of the variables $x_{t}$, where $x_{t}$ denotes the number of voters of type $t$.


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- The inequalities above define a polytope $n \mathbb{P}$ with dimension $m!$, lying in the simplex $n \mathbb{S}:=\left\{x \mid \sum_{t} x_{t}=n, \forall t x_{t} \geq 0\right\}$. The intersection of two $S_{t}$ corresponds to the polytope with the union of constraints.


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- Under IAC, the probability distribution is uniform on $\mathbb{S}$, so probabilities reduce to counting lattice points in the polytope.
- The asymptotic leading term of the probability equals the volume of the normalized polytope $\mathbb{P}$ divided by that for $\mathbb{S}$. Such volumes can be computed by publicly available software implementing standard algorithms.


## Linear system example: Borda, $m=3$

- Suppose that the sincere election result is $|a|>|b| \geq|c|$, and we take $t=c b a, t^{\prime}=b c a$. Order the types $a b c, a c b, b a c, b c a, c a b, c b a$ and let $n_{i}$ be the size of $\mathcal{V}_{i}$.


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- Let $|a|^{\prime}$ denote $a$ 's score after a strategic attempt as above, etc. Then the attempt is successful if and only if $|b|^{\prime} \geq|a|^{\prime},|c|^{\prime}$. We can express $|a|^{\prime}$, etc, as a linear combination of the $n_{i}$. This yields $n_{i} \geq 0, \sum_{i} n_{i}=n$, and

$$
\begin{aligned}
& 0 \leq n_{1}+n_{2}-n_{3}-n_{4} \\
& 0 \leq n_{3}+n_{4}-n_{5}-n_{6} \\
& 0 \leq-n_{1}-n_{2}+n_{3}+n_{4}+n_{6} \\
& 0 \leq-n_{1}-n_{2}+2 n_{3}+2 n_{4}-n_{5}+2 n_{2}
\end{aligned}
$$

## Numerical results for $m=3$

Table: Asymptotic probability under IAC of a situation being (safely) manipulable.

| scoring rule | P (manip) | P (safely) | P (safely $\mid$ manip) |
| :---: | :---: | :---: | :---: |
| Plurality | 0.292 | 0.292 | 1.00 |
| (3,1,0) | 0.422 | 0.322 | 0.76 |
| Borda | 0.502 | 0.347 | 0.69 |
| $(3,2,0)$ | 0.535 | 0.330 | 0.62 |
| $(10,9,0)$ | 0.533 | 0.264 | 0.49 |
| Antiplurality | 0.525 | 0.222 | 0.42 |

## Discussion of results

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- The asymptotic conditional probability of being safely manipulable given manipulable decreases as the weight given to the second ranked alternative increases.


## Extensions

- It seems natural to consider the uniform distribution on profiles (IC). However we don't expect this to be interesting for positional scoring rules, at least for large $n$. Reason: with high probability the differences in candidate scores are of order $\sqrt{n}$ but the number of voters of each type is of order $n$. Thus some types of votes will be safe almost always, other types almost never.


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－Is there a polynomial time algorithm for ExistsSafe，for a general positional scoring rule？We know there is one for easy rules like plurality and antiplurality．What about Borda？ （Recent：Egor lanovski appears to have solved this）．三 $\quad$ 〇Qく

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－What happens when we extend to coalitional manipulation，or some intermediate model？

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- For safe manipulation, $\mathcal{M}=\mathcal{V}_{t}$ for some fixed $t$. Suppose that $t$ and $t^{\prime}$ are specified. The players in $\mathcal{M}$ have a unique dominant strategy in a given profile ("all switch to $t^{\prime \prime \prime}$ ) if and only if the profile is safely manipulable.


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- For safe manipulation, $\mathcal{M}=\mathcal{V}_{t}$ for some fixed $t$. Suppose that $t$ and $t^{\prime}$ are specified. The players in $\mathcal{M}$ have a unique dominant strategy in a given profile ("all switch to $t^{\prime \prime \prime}$ ) if and only if the profile is safely manipulable.
- What happens in other cases? What do symmetric (mixed) Nash equilibria look like? What if we only want safety with high probability?

